

**3rd RF Summit Finland
Oulu, 19.3.2025**

Recent Advances in Digital Predistortion Methods

Lauri Anttila, Arne Fischer-Bühner*, Joel Fernandez, and Mikko Valkama
Tampere University

* also with Nokia Bell Labs, Antwerp, Belgium

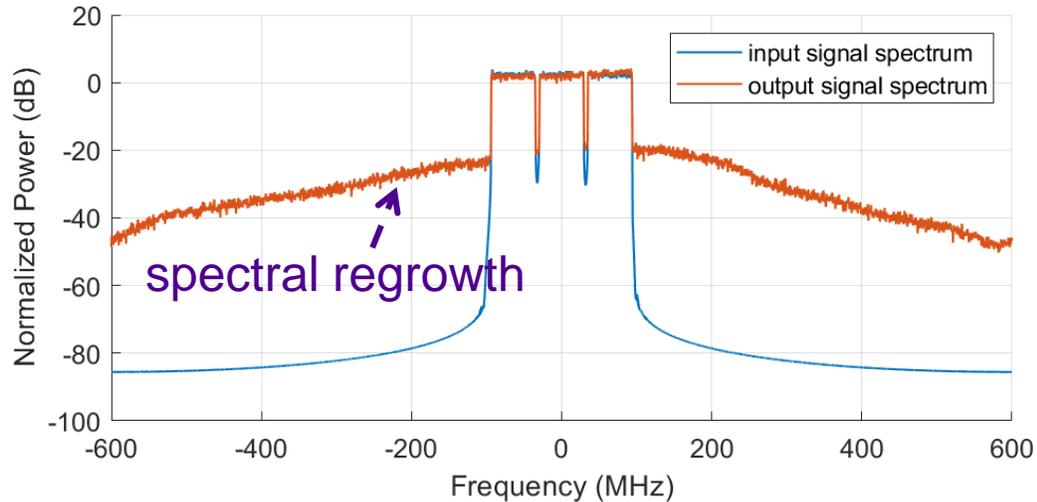
Outline

- Power amplifier nonlinearity and DPD – Quick recap
- **Neural networks for PA linearization**
- **Phase-normalized NNs**
- **Multi-antenna DPD**
- Summary and Future work
- References

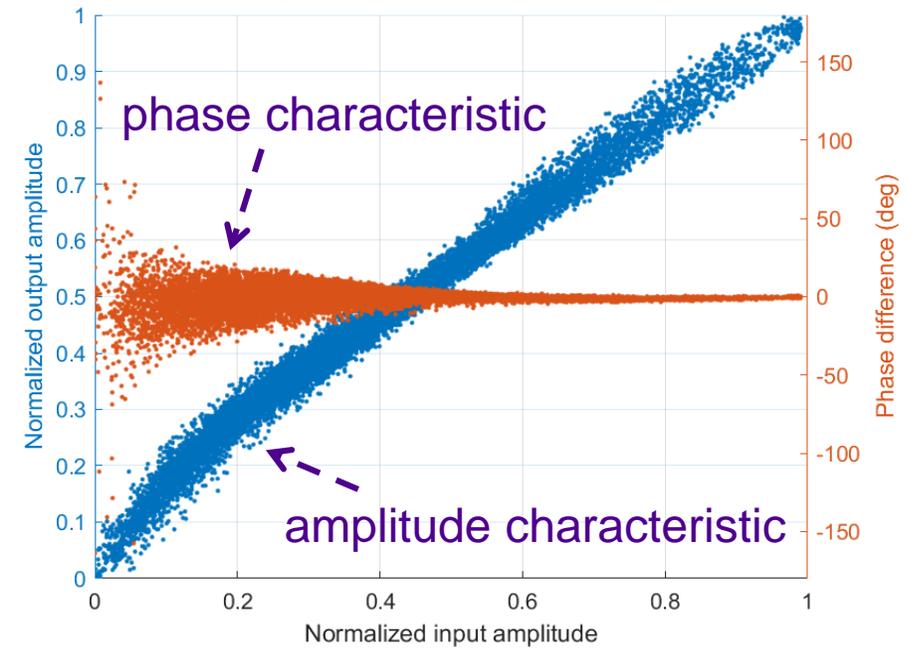
PA distortion Problem

Complex valued envelope/baseband signals

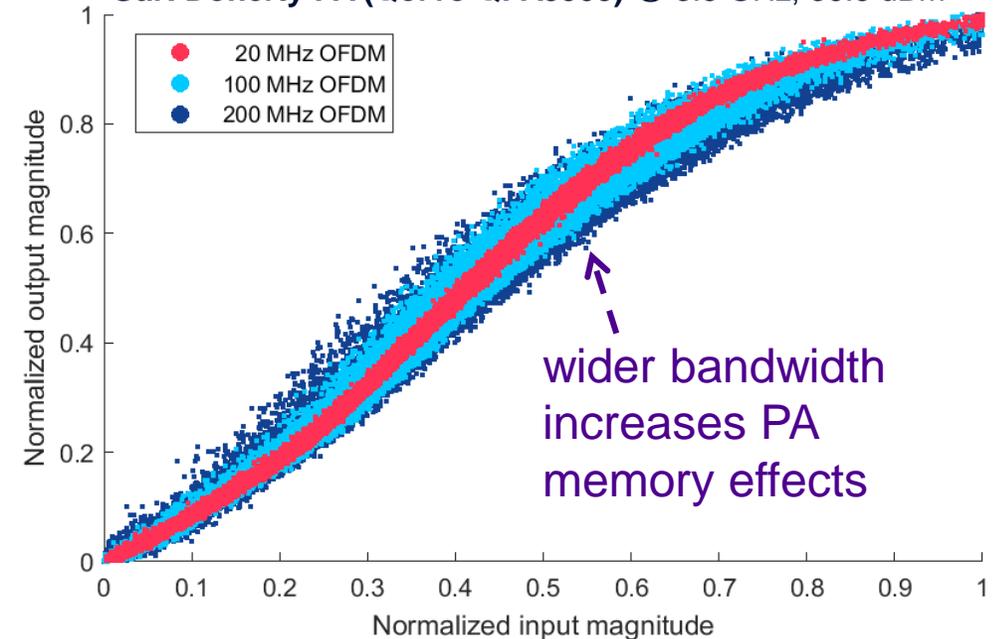
- nonlinear distortion
- dynamic distortion (“memory”)
- *time-variant distortion -> solved by adaptation*



GaN Doherty PA (RTH18008S-30) @ 1.8 GHz, 39 dBm



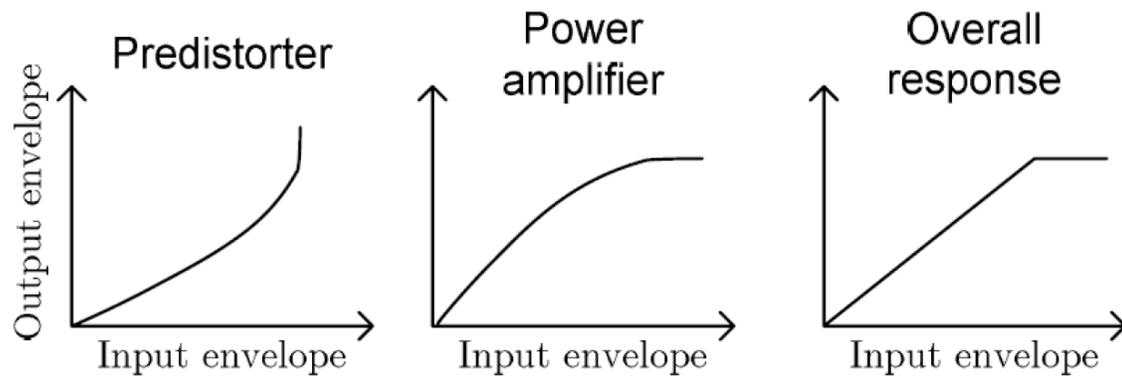
GaN Doherty PA (Qorvo QPA3503) @ 3.5 GHz, 36.5 dBm



Digital predistortion (DPD)

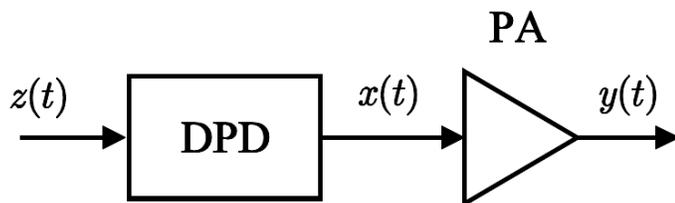
DPD means preprocessing the digital transmit signal such that when put through a nonlinear PA, the overall response is more linear

- Thus, naturally, nonlinear preprocessing is needed
- The DPD models are based on PA behavioral models



DPD targets

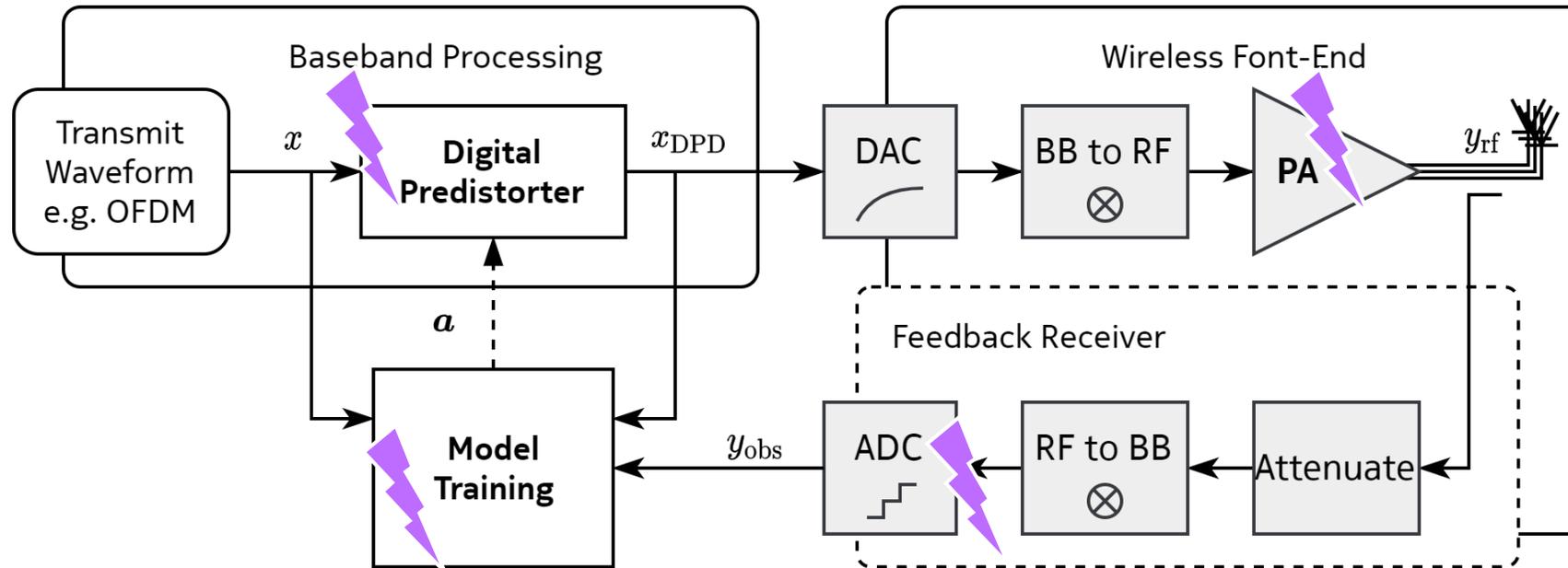
- Improve EVM
- Improve ACLR
- Reduce spurious emissions
- Improve transmitter power efficiency with given emission constraints



DPD Challenges

- *capable models required to compensate distortion*
- low-complexity requirement for efficient inference

- wide-band signals stimulate strong dynamic distortion
- new PA technologies (GaN, HEMT, etc.)
- *antenna coupling, load modulation* → *beam-dependent DPD*



- model identification complexity
- real-time adaptation to signal changes
- beam adaptation

- high linearity and bandwidth requirement
- sampling rate is driving ADC energy / cost
- Observation architecture in multi-antenna systems?

Neural Network DPD

Why AI/ML?

Motivation

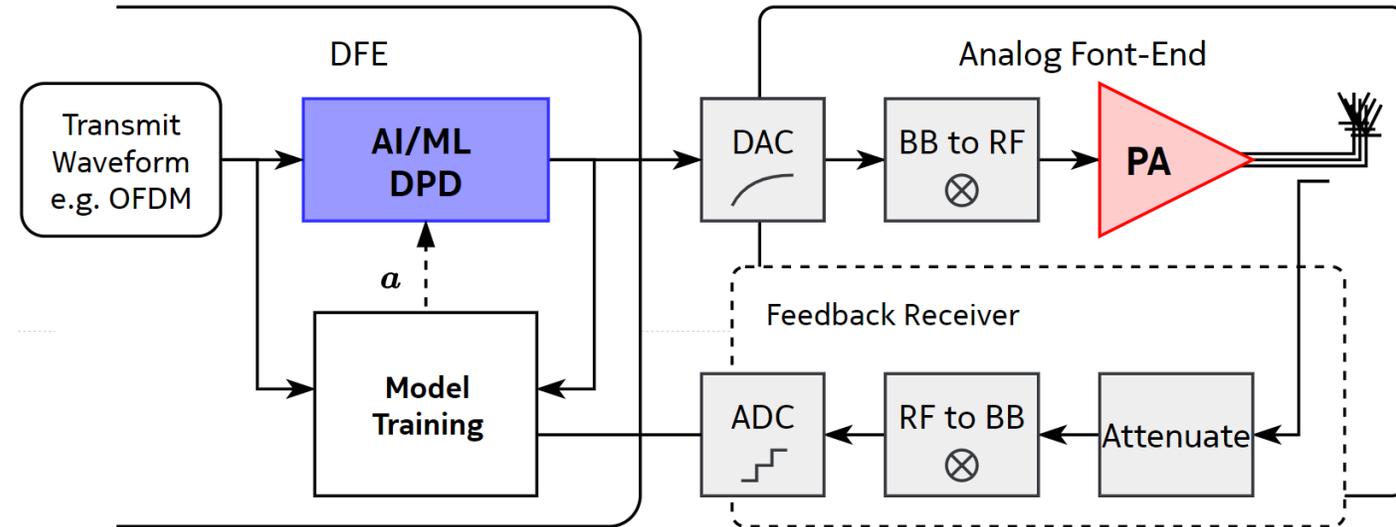
6G DPD requirements

- low area and energy footprint
- excellent linearization (wideband, FCC)
- high flexibility

AI/ML offer

- NN offer high modeling capacity with good generality
- fully data-driven approach, low manual tuning effort

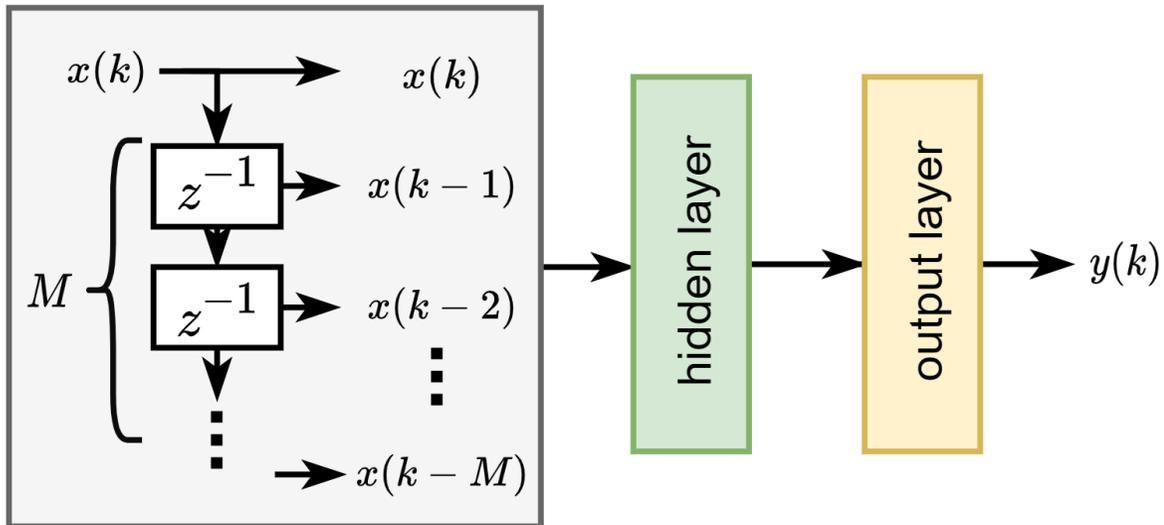
Q: Can AI/ML DPD deliver superior linearity with competitive complexity/cost?



Modeling dynamic distortion with NNs

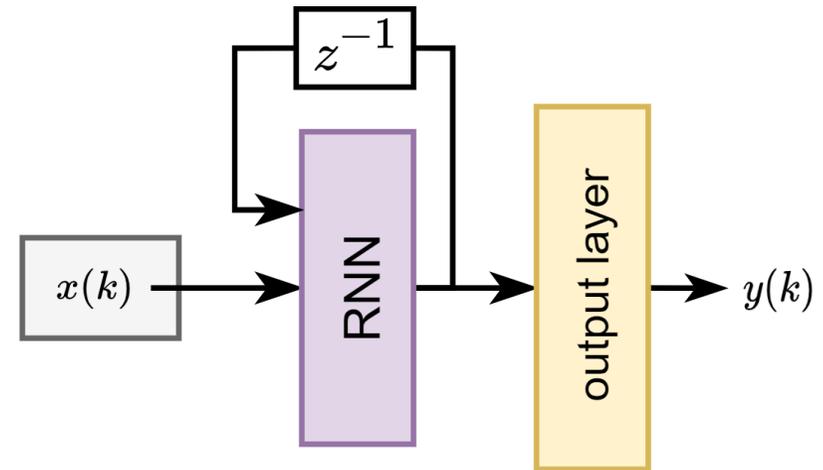
NN architectures

Time-delay Neural Network



- “simpler” architecture
- limited memory depth

Recurrent Neural Network



- more complex training and structure
- infinite memory depth (in theory)
- closer to PA physics

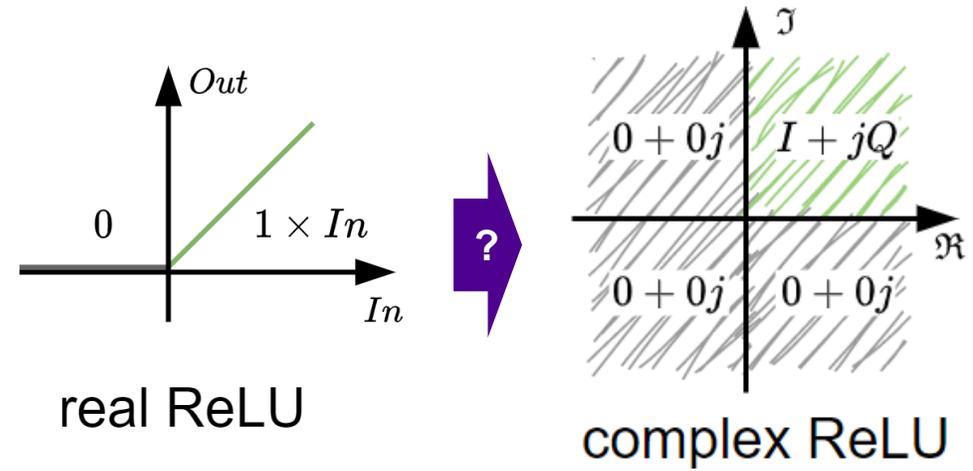
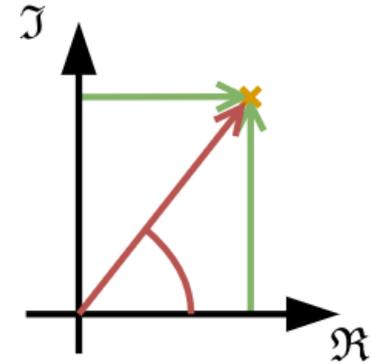
Complex-valued baseband signals

...with real-valued NN structures

- decompose cartesian: real & imaginary
 - *joint or separate processing ?*
 - *support for complex-valued arithmetic?*

- decompose polar: magnitude & angle
 - *significance of phase depends on magnitude ?*
 - *support for $\pm\pi$ periodicity ?*

- complex-valued neural network
 - *non-obvious choice of activation function ?*
 - *complication with back-propagation ?*
 - *theory and tools not fully developed*



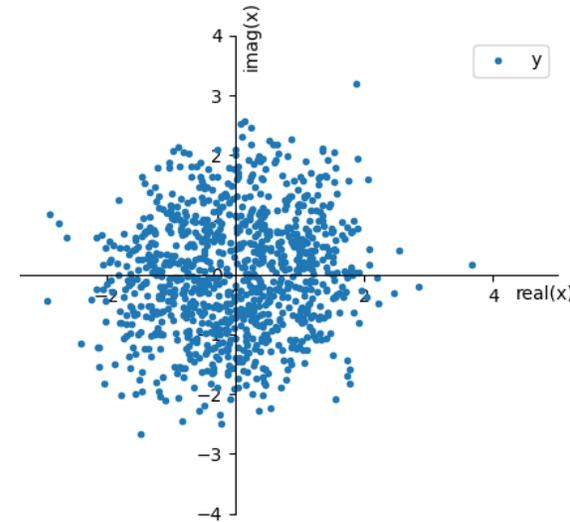
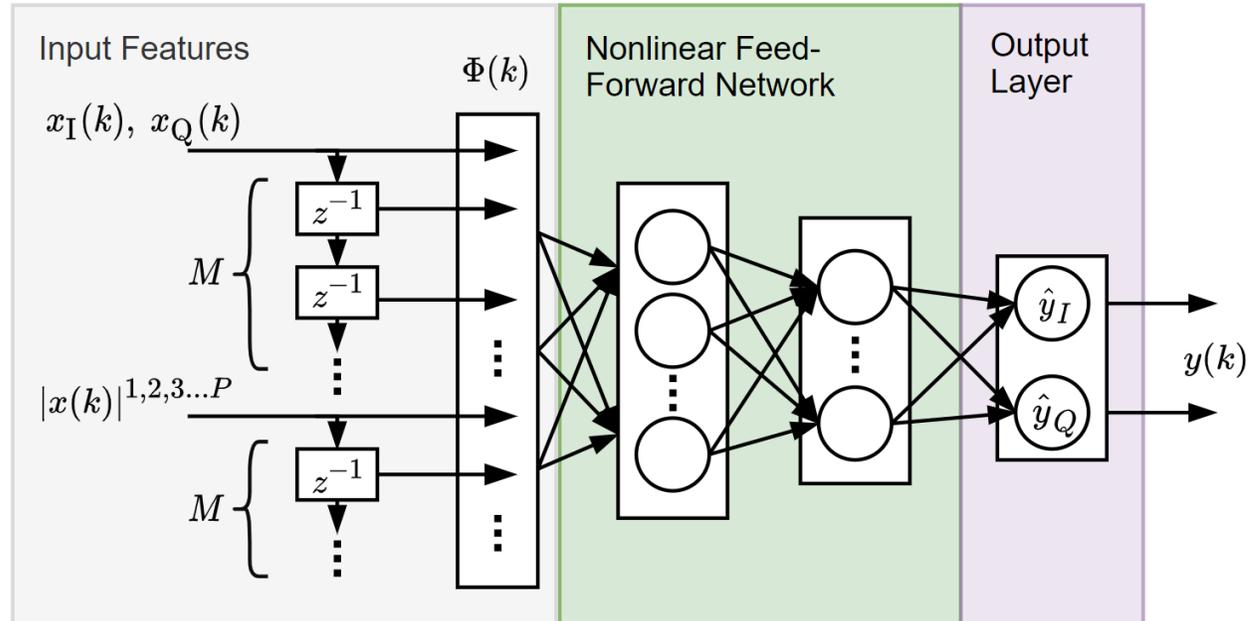
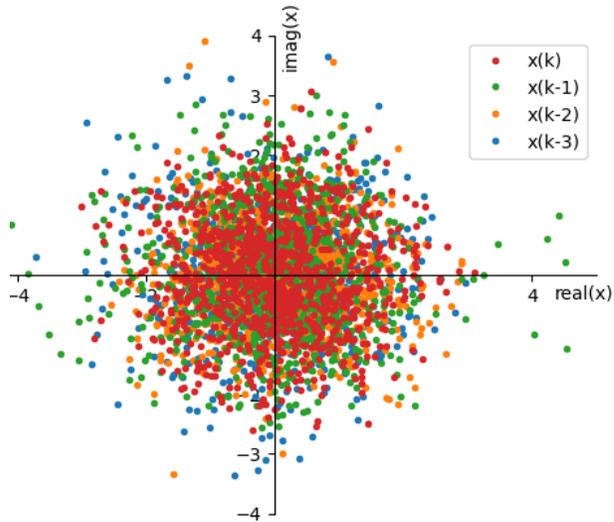
Phase-Normalized NN

Augmented real-valued TDNN

Decompose real & imaginary

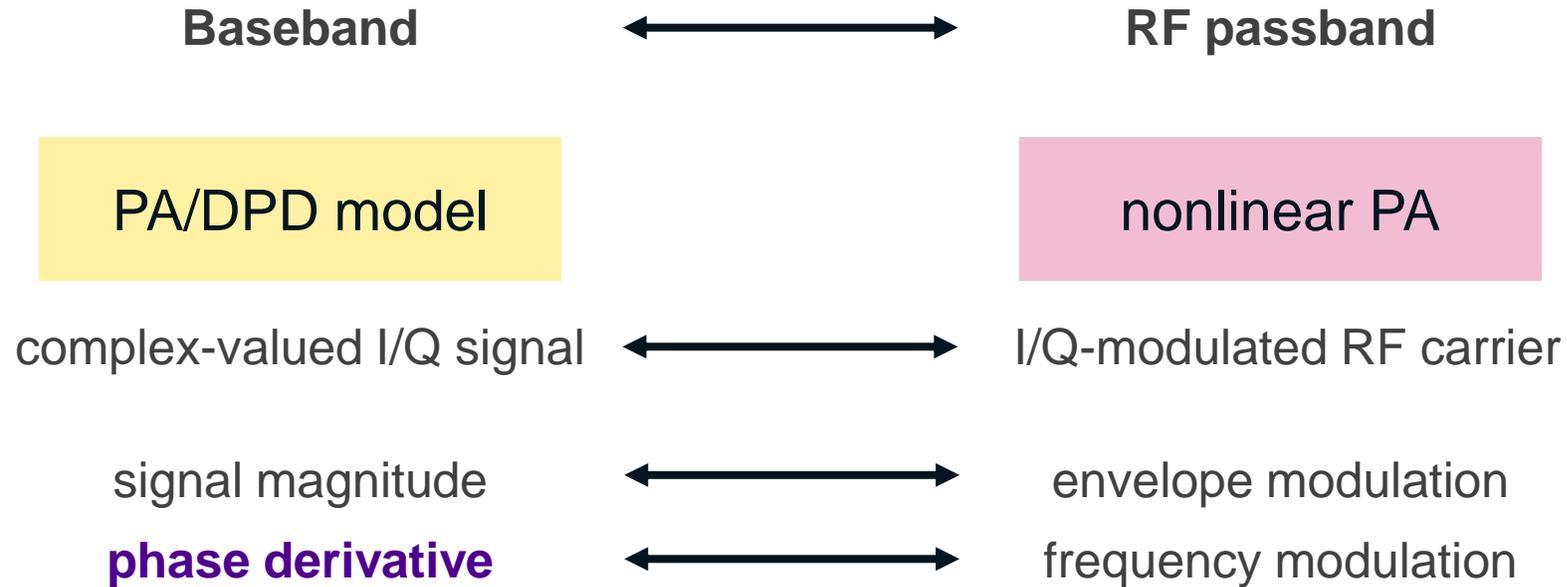
separation of real/imaginary part (I/Q)
 → real-valued processing

additional absolute/envelope inputs $|x(k)|$
 → nonlinear effects depend on envelope



Issues: 1) can also express non-physical RF effects
 2) inefficient at processing of complex data

Distortion-phase dependency



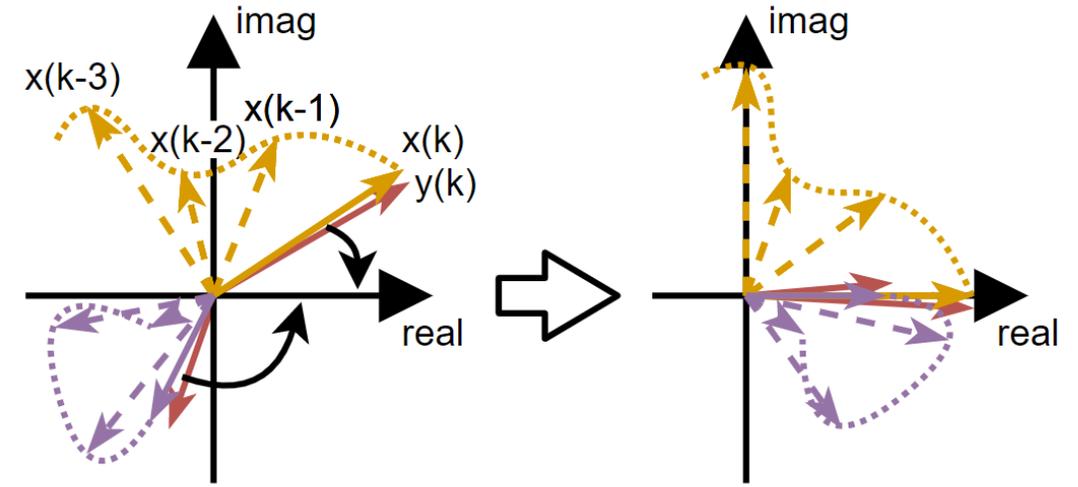
- ❑ Instantaneous baseband signal phase is meaningless in the RF domain
- ❑ Only *phase derivative* contributes to PA distortion

Phase normalization

Proposed solution

process only magnitude and phase trajectory instead of I/Q decomposed signal

- rotating the input vectors with angle of current input



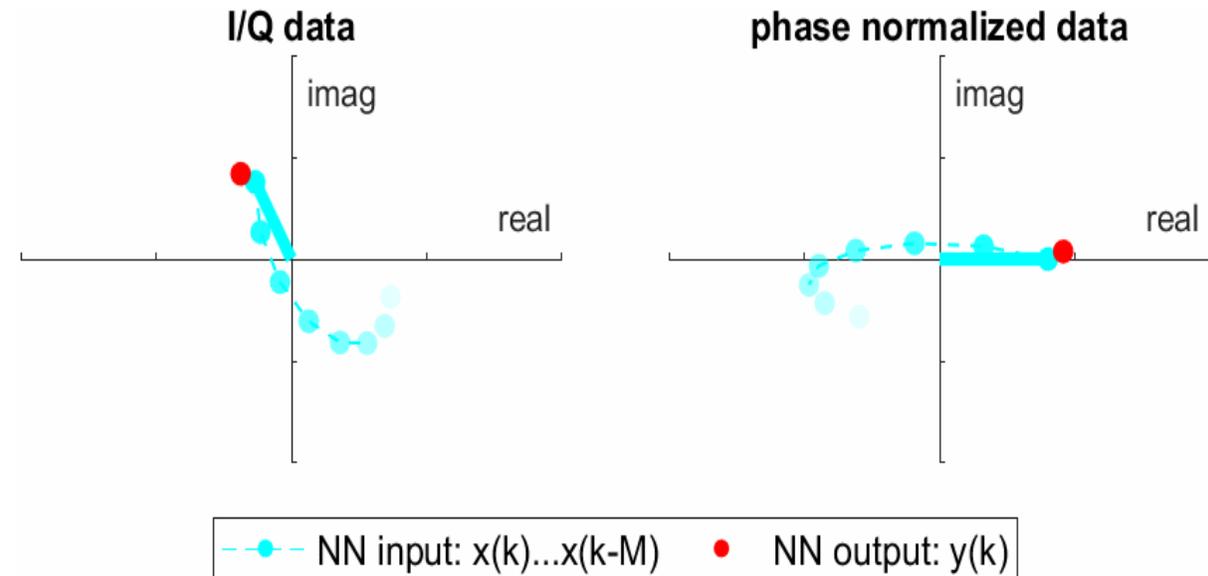
Normalization factor: $r(k) = x^*(k)/|x(k)|$

Phase normalized NN inputs:

$$\begin{aligned} \mathbf{X}(k) &= r(k)[x(k), x(k-1), x(k-2), \dots, x(k-M)] \\ &= [|x(k)|, r(k)x(k-1), \dots, r(k)x(k-M)] \end{aligned}$$

NN output phase recovery:

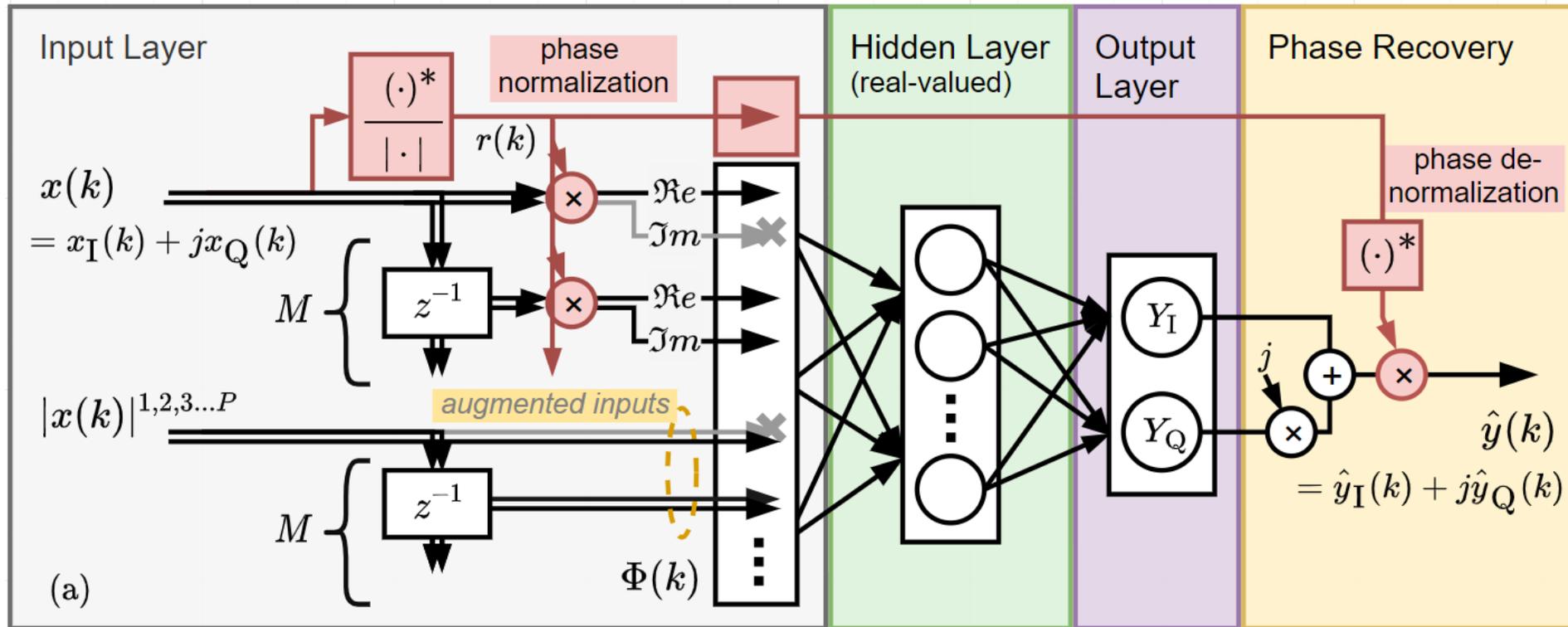
$$y(k) = r^*(k) f_{\text{NN}}(\mathbf{X}(k))$$



Phase normalized time-delay NN PNTDNN

Embedded into augmented real-valued time-delay NN (ARVTDNN)

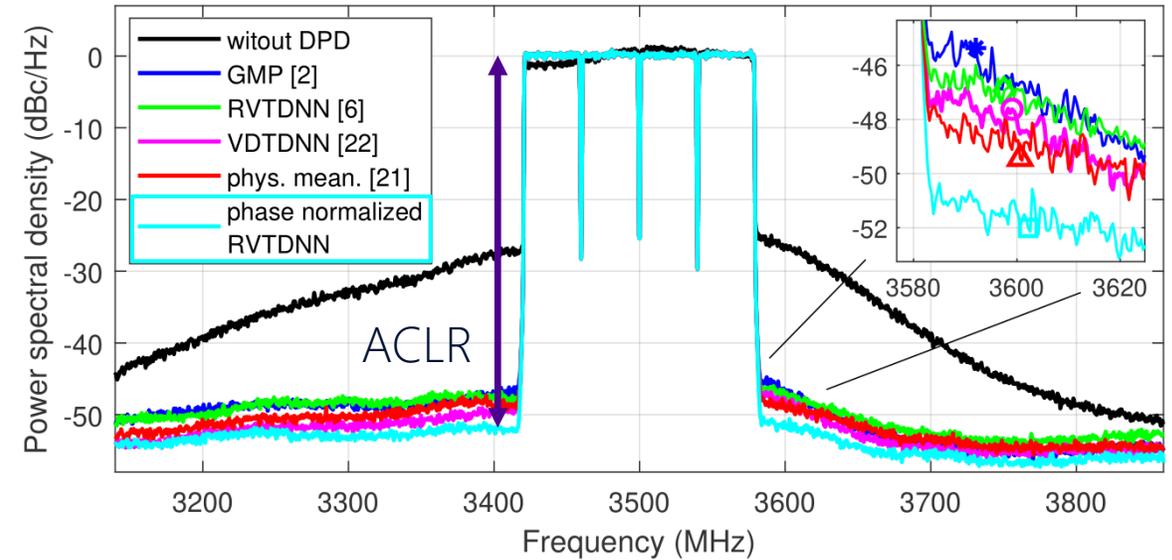
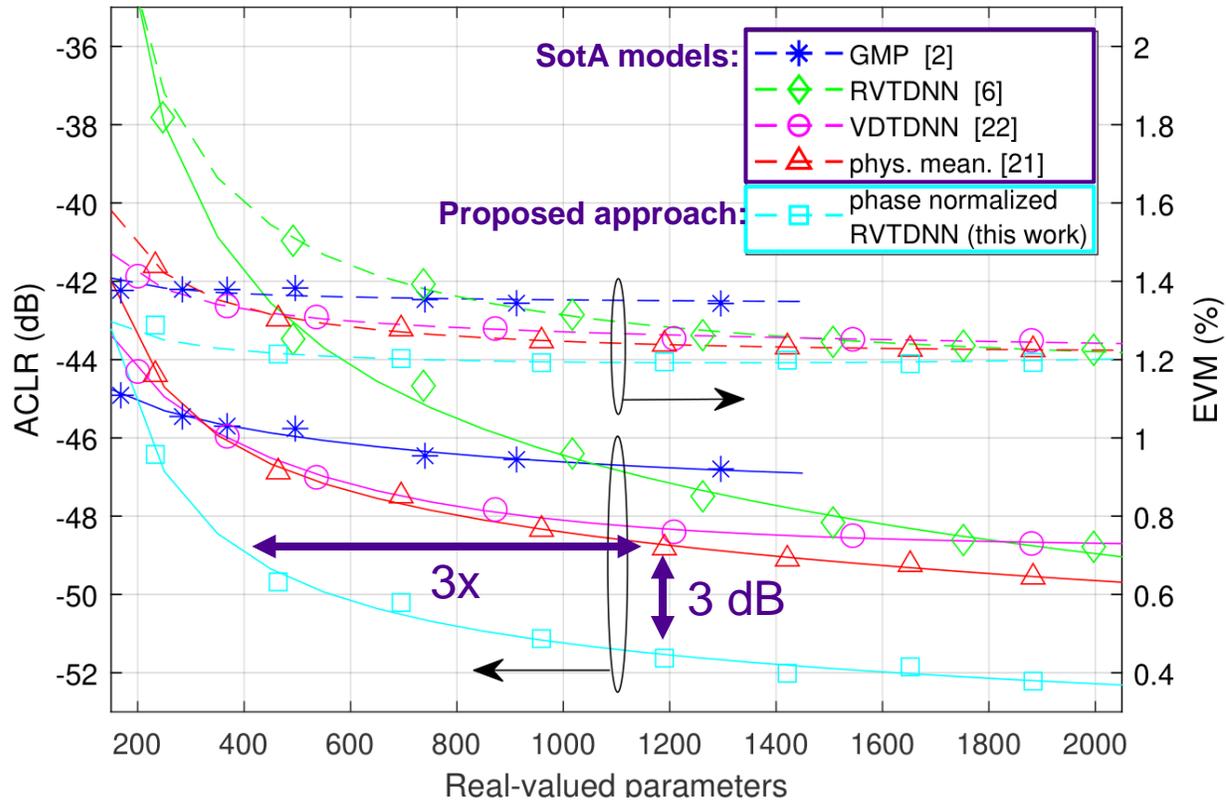
baseband processing
real-valued NN
passband nonlinearity



DPD linearization results

DUT: QPA3503, 3.5 GHz, 160 MHz, 8.5 dB PAPR

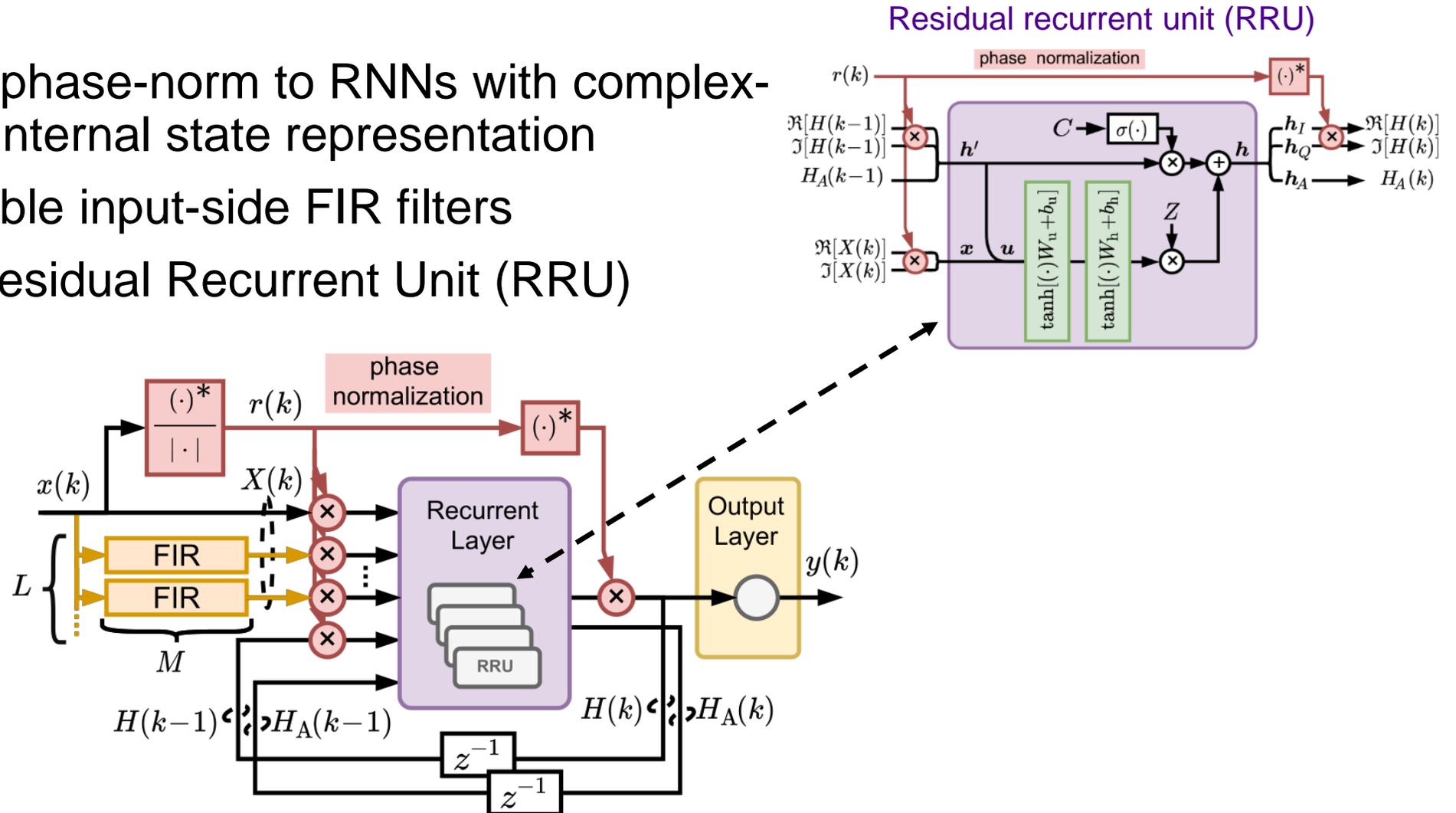
Generalized memory polynomial (GMP)
 Real-valued time delay NN (RVTDNN)
 Vector decomposed time-delay NN (VDTDNN)
 "Physically Meaningful" DPD model (Phys. Mean.)



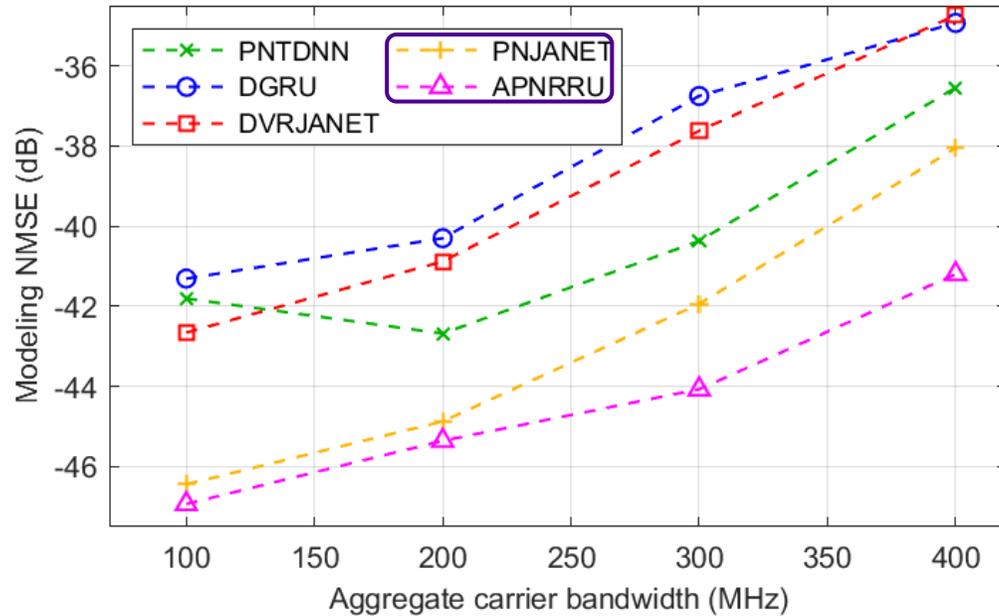
- **3 dB lower/better ACLR**
 (compared with best published SotA NN)
- **1/3 model complexity**
 (similar performance)

Augmented phase-normalized RRU (APNRRU)

- incorporated phase-norm to RNNs with complex-valued RNN internal state representation
- added learnable input-side FIR filters
- utilized the Residual Recurrent Unit (RRU)



APNRRU – Wideband Modeling and DPD results

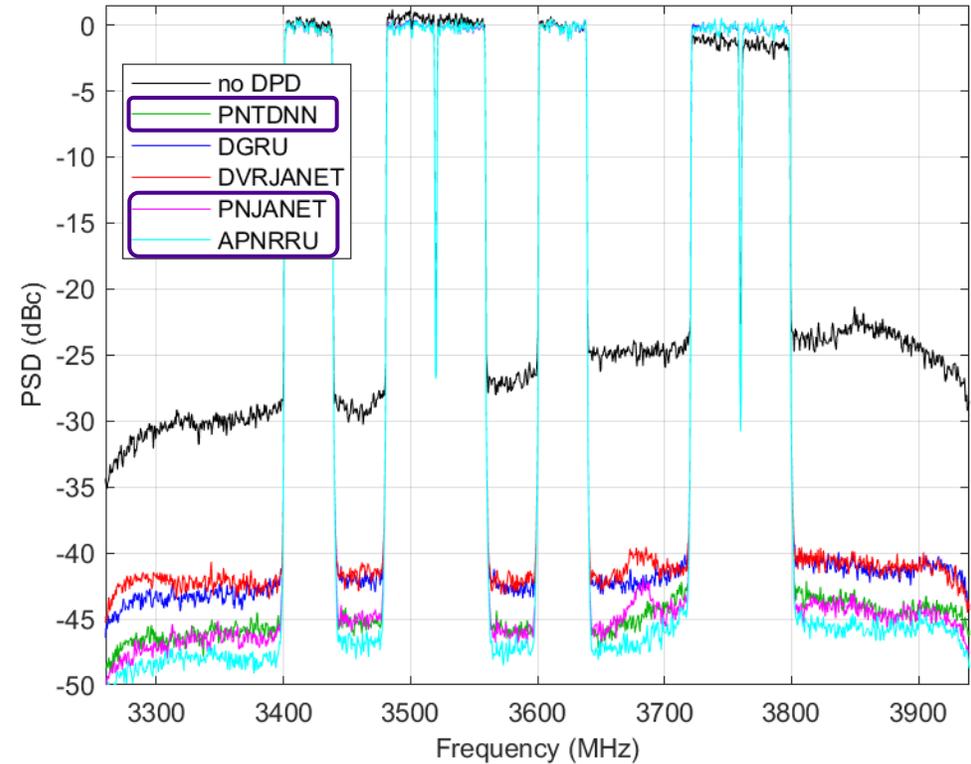


Dense GRU (DGRU)

Decomposed Vector Rotation JANet (DVR-JANet)

Phase normalized time-delay NN (PNTDNN)

LDMOSE/GaN two-stage PA (NXP A5M36TG040-TC) @ 3.6 GHz



Name	Parameters	NMSE (dB)	ACLR (dB)	EVM (%)
without DPD	–	-17.60	-23.52	6.16
PNTDNN	1110	-33.38	-43.18	1.80
DGRU	1045	-32.18	-40.42	1.71
DVRJANET	1098	-32.36	-40.19	1.56
PNJANET	1026	-34.63	-43.80	1.48
APNRRU	1041	-35.93	-45.24	1.24

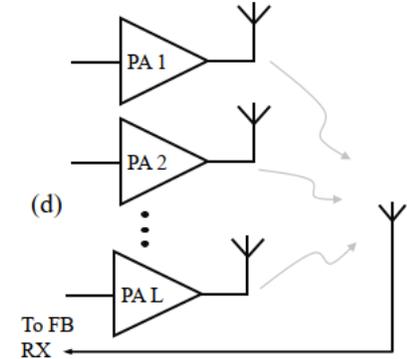
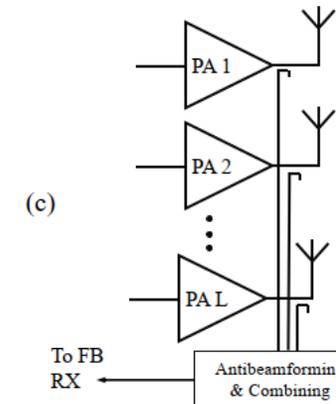
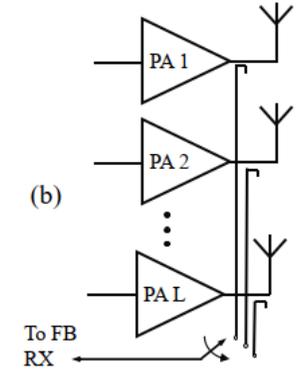
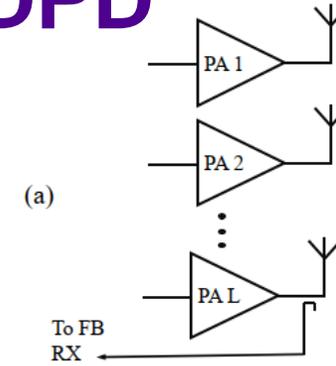
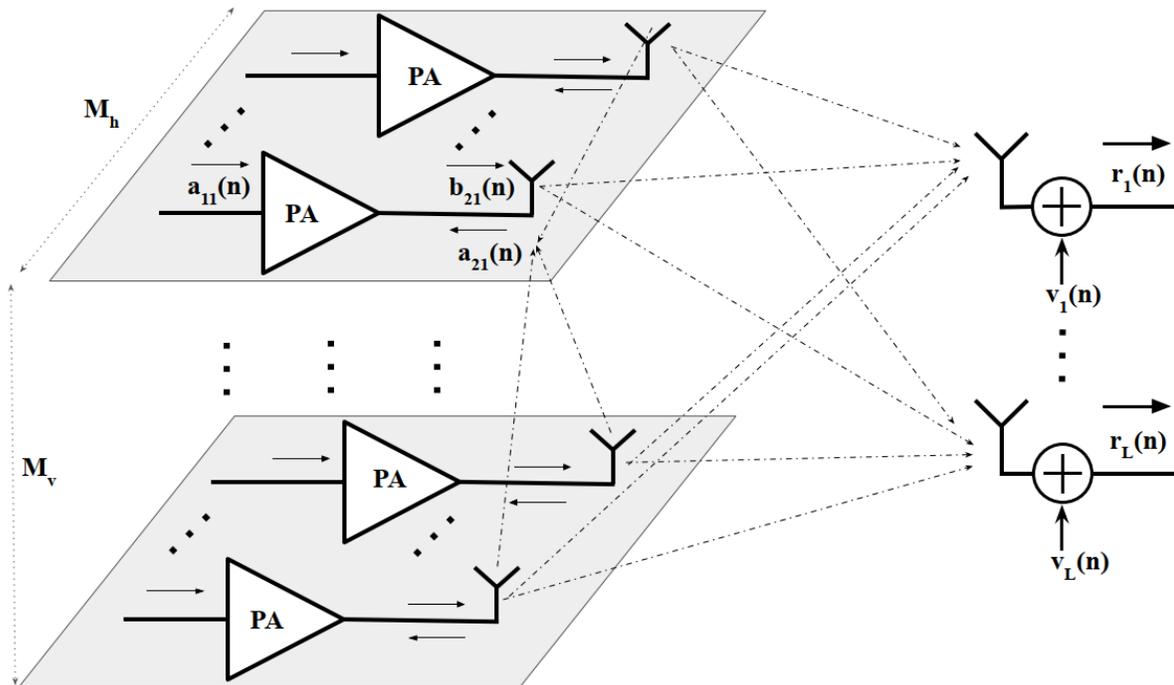
Multi-antenna DPD

Some Challenges in Multi-Antenna DPD

Antenna coupling and **PA load modulation**

→ **Cross-modulation** between antenna signals

→ **Beam-dependent nonlinear distortion**



How to arrange feedback for DPD learning?

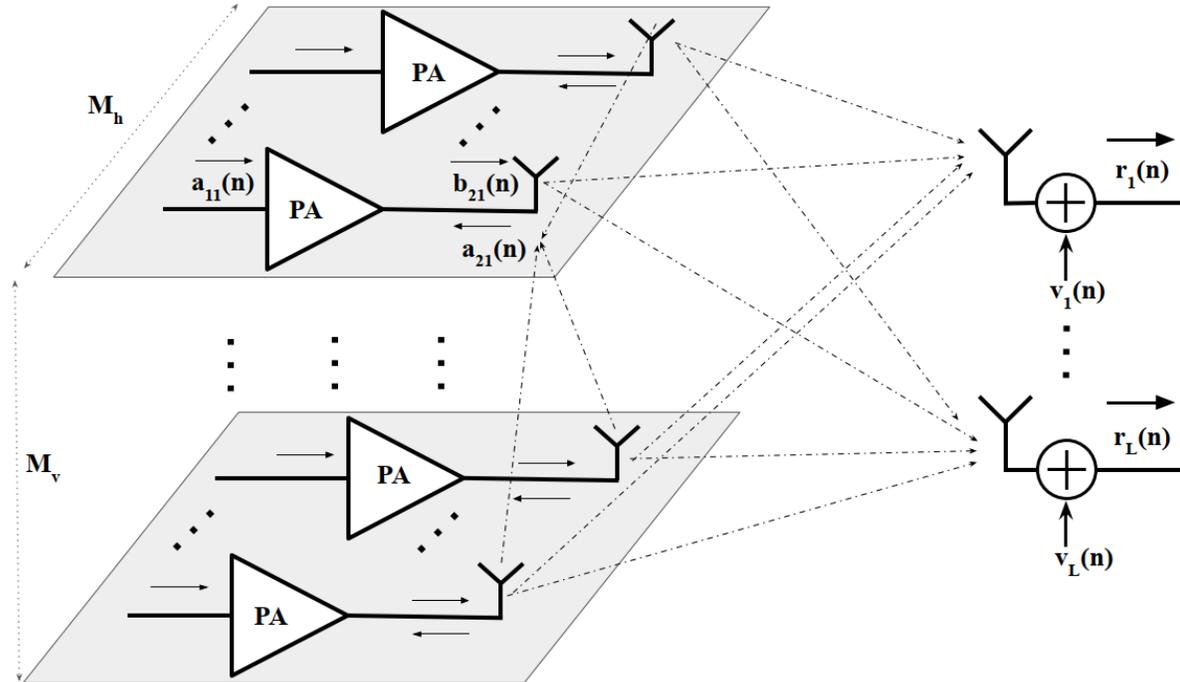
- a) Single feedback
- b) Shared feedback
- c) Combined-feedback
- d) Over-the-air (OTA) feedback
- e) Dedicated feedback (not shown)

Modeling Multi-Antenna TX under Load Modulation

Problem: PA forward model estimation from OTA observations

We recently developed an iterative algorithm, under the following assumptions:

- Minimum two observation antennas/RXs required
 - Dual-input memory polynomial models for modeling the nonlinear PAs under load modulation
 - Beam-sweeping observations over $\geq K$ directions
 - Coupling coefficients (S-parameters) between antennas are known
-
- The estimated PA models are used in a subsequent step for DPD learning



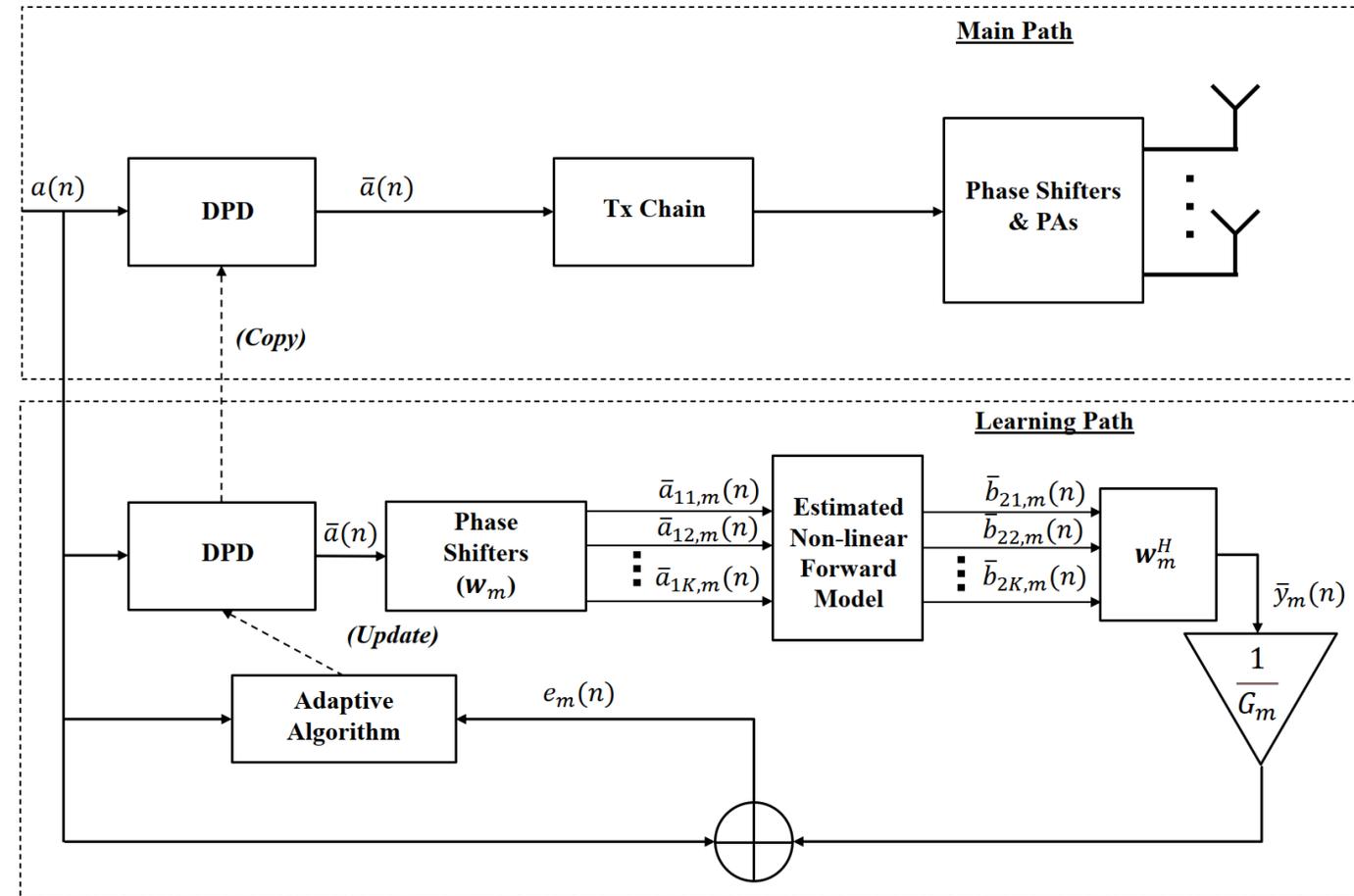
$$b_{2k} = \sum_{p=0}^{(P-1)/2} \alpha_{kp} a_{1k}^{(p+1)} a_{1k}^{*p} + \sum_{p=0}^{(P-1)/2} \beta_{kp} a_{1k}^p a_{1k}^{*p} a_{2k} + \sum_{p=1}^{(P-1)/2} \gamma_{kp} a_{1k}^{(p+1)} a_{1k}^{*(p-1)} a_{2k}^*$$

$$a_{2k} = \sum_{i=1, i \neq k}^K \lambda_{ki} b_{2i}$$

DPD Architecture for Phased Array

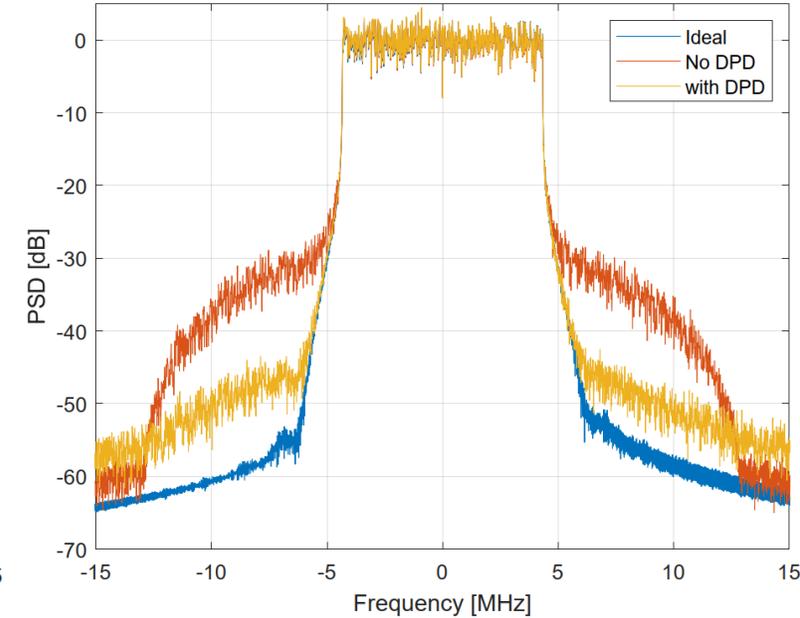
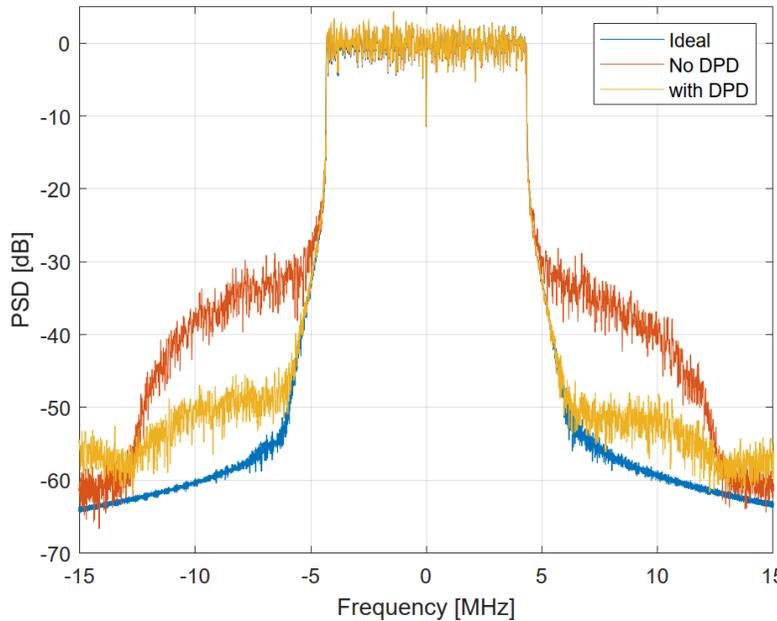
Utilizing the estimated nonlinear forward model, we developed a DPD solution, which

- Accounts for PA load modulation caused by antenna coupling.
- Enables on-line adaptation while steering the beam.
- Has low computational complexity.
- Addresses beam-dependency of nonlinear distortions, greatly improving transmitter linearity.



Proof-of-Concept Measurement Results

- Measured PA signals with load modulation, utilizing a coupling emulation technique
- 4x1 array coupling model
- Successful linearization over different beamforming angles
- First OTA DPD technique that can handle load modulation!



Beamforming angle (in degrees)	Simulation with a measured PA model				Measurement with an actual PA array			
	EVM (w/o DPD)	EVM (with DPD)	ACPR (w/o DPD)	ACPR (with DPD)	EVM (w/o DPD)	EVM (with DPD)	ACPR (w/o DPD)	ACPR (with DPD)
-60°	5.207%	3.049%	-35.82	-52.29	5.427%	3.001%	-35.37	-50.07
-30°	4.571%	2.418%	-36.00	-53.28	5.066%	2.738%	-35.29	-50.36
0°	5.038%	3.006%	-35.63	-50.01	5.154%	2.793%	-35.50	-46.90
30°	4.591%	2.605%	-36.55	-51.25	5.183%	2.781%	-35.51	-49.60
60°	4.964%	2.846%	-36.57	-51.15	5.910%	3.504%	-35.14	-49.65

Summary and Future Work

- Phase-normalized NN for DPD
 - Time-delay and recurrent variants developed
 - State-of-the-art performance at given complexity
- Multi-antenna DPD under load modulation
 - Developed OTA based learning solution for phased-array TX – First solution
 - Developed NN model for forward modeling and DPD in digital MIMO TX – SoTA perf
- On-going and Future work
 - Merging these two study lines
 - Further research on OTA-based multi-antenna DPD
 - Developing the ML/NN-based solutions further:
 - complexity reductions, learning architecture research, MIMO measurement studies, design exploration towards implementation

Literature

- [1] A. Fischer-Bühner, L. Anttila, M. Dev Gomony and M. Valkama, "Phase-Normalized Neural Network for Linearization of RF Power Amplifiers," in *IEEE Microwave and Wireless Technology Letters*, Sept. 2023, doi: 10.1109/LMWT.2023.3290980.
- [2] A. Fischer-Bühner, L. Anttila, M. Turunen, M. Dev Gomony and M. Valkama, "Augmented Phase-Normalized Recurrent Neural Network for RF Power Amplifier Linearization," in *IEEE Transactions on Microwave Theory and Techniques*, vol. 73, no. 1, pp. 412-422, Jan. 2025, doi: 10.1109/TMTT.2024.3484581.
- [3] J. Fernandez et al., "Over-the-Air Linearization of Phased Array Transmitters Affected by Load Modulation," *IEEE Transactions on Circuits and Systems I: Regular Papers*, doi: 10.1109/TCSI.2025.3527701. (Early Access)
- [4] J. Fernandez et al., "Neural Network based Nonlinear Forward Model Identification for Digital MIMO Arrays under Load Modulation," *IEEE IMS-2025* (accepted for publication).
- [5] K. Hausmair, S. Gustafsson, C. Sánchez-Pérez, P. N. Landin, U. Gustavsson, T. Eriksson, and C. Fager, "Prediction of nonlinear distortion in wideband active antenna arrays," *IEEE Transactions on Microwave Theory and Techniques*, vol. 65, no. 11, pp. 4550–4563, 2017.
- [6] Z. A. Khan, E. Zenteno, P. Händel, and M. Isaksson, "Digital predistortion for joint mitigation of I/Q imbalance and MIMO power amplifier distortion," *IEEE Transactions on Microwave Theory and Techniques*, vol. 65, no. 1, pp. 322–333, 2017.
- [7] P. Jaraut, M. Rawat, and F. M. Ghannouchi, "Composite neural network digital predistortion model for joint mitigation of crosstalk, I/Q imbalance, nonlinearity in MIMO transmitters," *IEEE Transactions on Microwave Theory and Techniques*, vol. 66, no. 11, pp. 5011–5020, 2018.